



Tips and tricks for cost function of complex building optimal controllers

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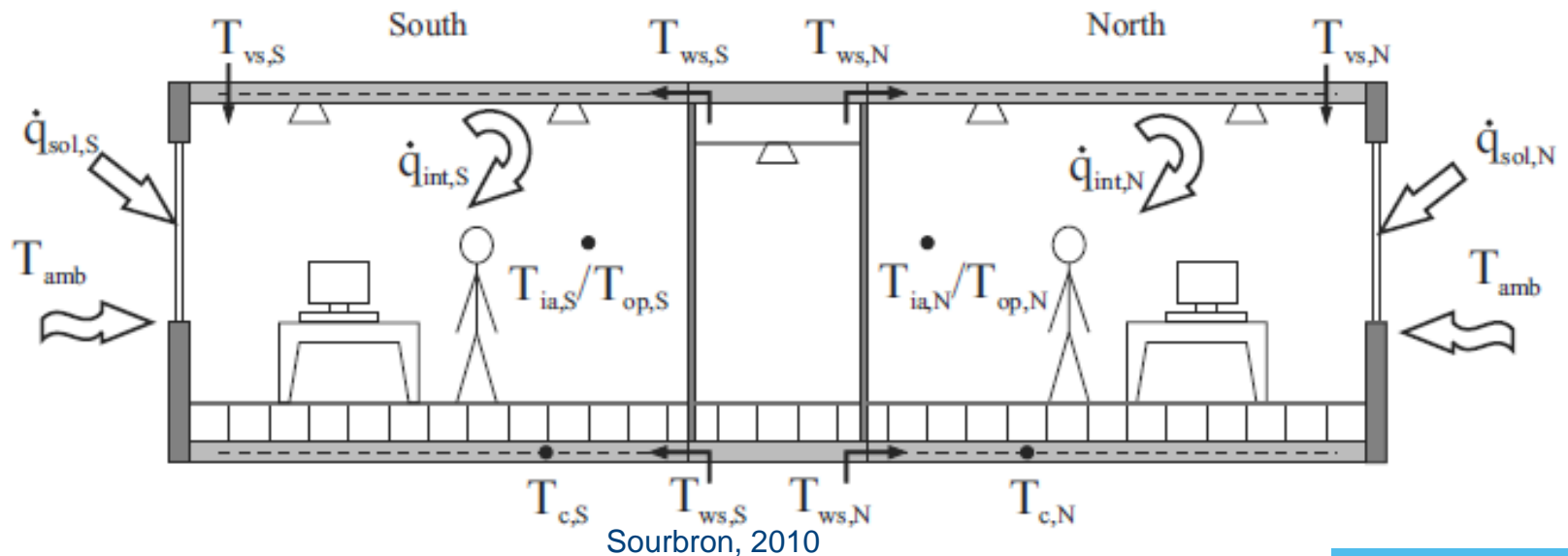
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Description of system

Building

- Three zones: north, south, corridor
- TABS
- VAV for north and south zone
- Internal gains
- Realistic parameters



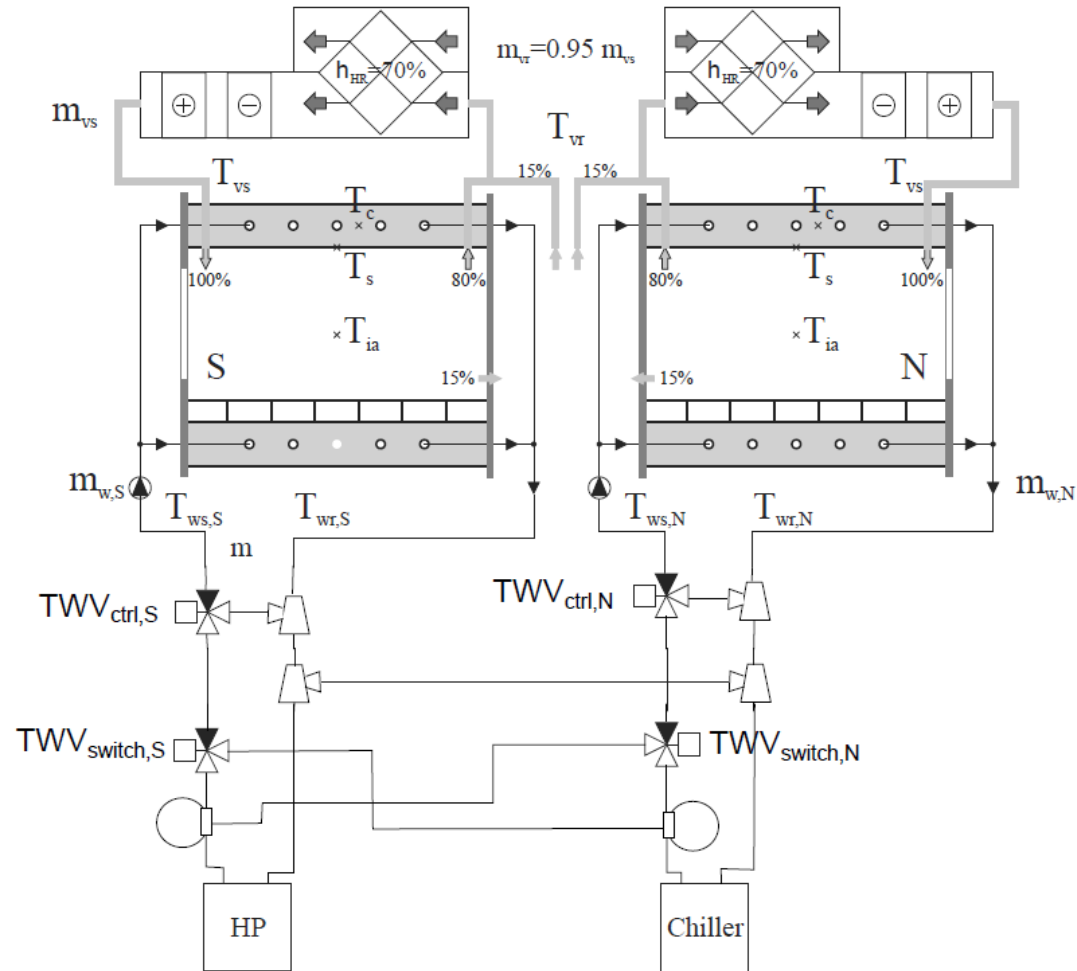
Description of system

Ventilation

- VAV
 - heating coil fed by gas-boiler
 - cooling coil fed by LT-chiller
 - heat recovery with by-pass
- Hygienic mass flow rate
- No latent heat or CO2

Heating system

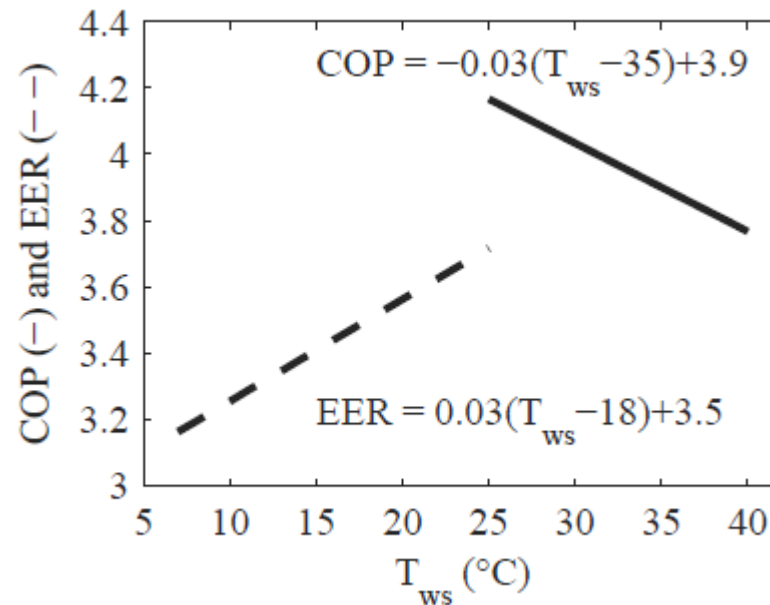
- Air-coupled heat pump for heating
- High temperature chiller
- Variable speed pumps
- Three-way valves



Description of system

Heat and cold production

- No dynamics
- Gas boiler ($\eta = 0.95$), LT-chiller (EER = 3)
- Heat pump and HT-chiller with variable COP / EER (based on Eurovent data)



Non-linearities of cost function

TABS and heat pump

- Inputs
 - HP supply temperature $T_{ws, hp}$
 - Zones supply temperature $T_{ws, z}$
 - Zones mass flow rate m_{zone}
- States
 - Water in tabs ($T_{ws, hp}$)

$$m_{vol} c_{p,w} \frac{dT_{vol}^N}{dt} = \dot{m}_z^N c_{p,w} (T_{ws,z}^N - T_{vol}^N) + G^N (T_{emb}^N - T_{vol}^N)$$

- Cost function

$$P_{el, hp} = \frac{Q}{COP} = \frac{c_{p,w} \dot{m}_{hp} (T_{wr, hp} - T_{ws, hp})}{-0.03 (T_{ws, hp} - (35 + 273.15)) + 3.9}$$

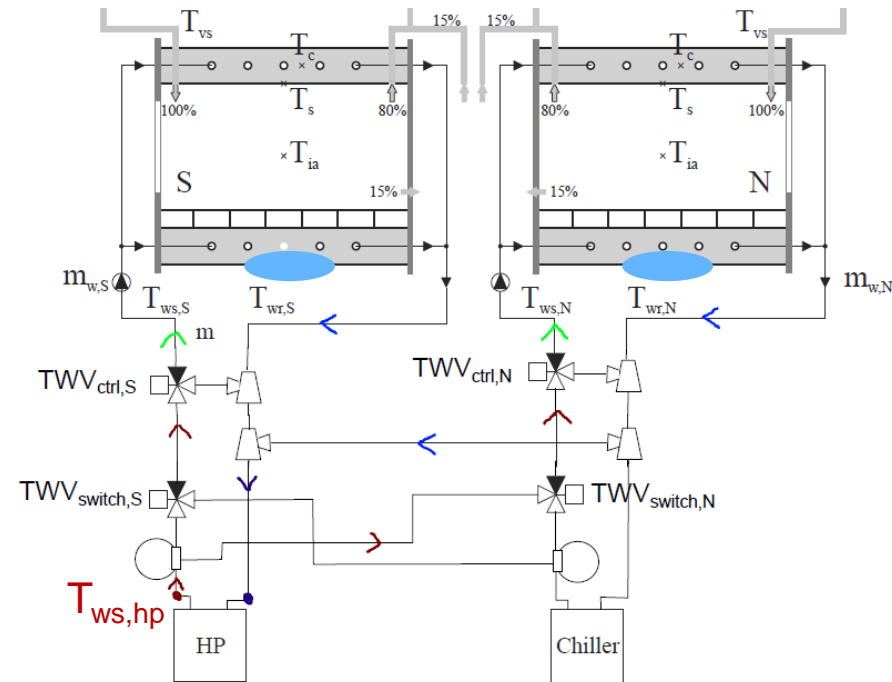
with

$$\dot{m}_{hp} = \dot{m}_{hp}^N + \dot{m}_{hp}^S$$

$$\dot{m}_{hp}^N = \dot{m}_{zone}^N \frac{T_{ws,z}^N - T_{vol}^N}{T_{ws, hp}^N - T_{vol}^N}$$

$$\dot{m}_{hp}^S = \dot{m}_{zone}^S \frac{T_{ws,z}^S - T_{vol}^S}{T_{ws, hp}^S - T_{vol}^S}$$

$$T_{wr, hp} = \frac{\dot{m}_{hp}^S}{\dot{m}_{hp}} T_{vol}^S + \frac{\dot{m}_{hp}^N}{\dot{m}_{hp}} T_{vol}^N$$



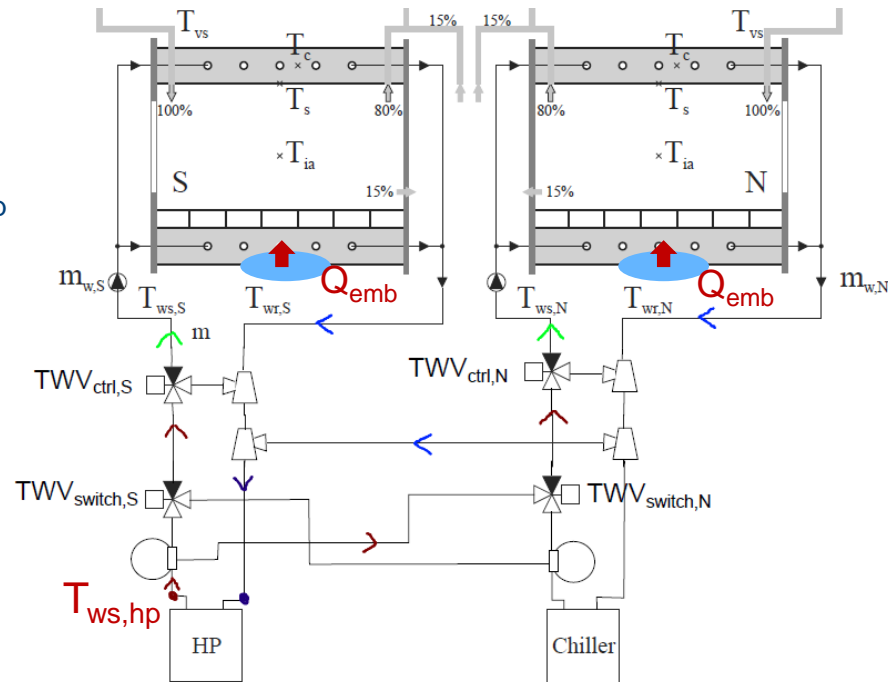
Non-linearities of cost function

TABS and heat pump

- optimize Q_{emb} instead of $m\Delta T \rightarrow Q_{emb} \approx Q_{hp}$
- Use heating curve for $T_{ws, hp} + modes$
- Neglect dynamics of water (small time constant)

- Cost function

$$P_{el, hp} = \frac{Q_{emb}^N + Q_{emb}^S}{-0.03 (T_{ws, hp} - (35 + 273.15)) + 3.9}$$



- + Linear cost function
- + Good approximation of production cost
- + For $Q_{emb} \rightarrow 0$, $\dot{m}_{zone} \rightarrow 0$

- Non-optimal *mode*, $T_{ws, hp}$ and \dot{m}_{zone}

- extra PID or static relationship: $\dot{m}_{zone} = \frac{Q_{emb}}{c_{p,w}} \left(T_{ws, hp} - T_{emb} - \frac{Q_{emb}}{G} \right)^{-1}$

Non-linearities of cost function

Ventilation

- Heat recovery (assuming constant ϵ for HEX):

$$T_{rec} = T_{amb} + \epsilon(T_{zone} - T_{amb})$$

- Mixed air using by-pass

$$V_{mix} \rho_a c_{p,a} \frac{dT_{mix}^N}{dt} = \dot{m}_{vent}^N c_{p,a} (-T_{mix}^N + \epsilon \text{BPF}^N (T_{amb} - T_{zone}^N) + (1 - \epsilon)T_{amb} + \epsilon T_{zone}^N)$$

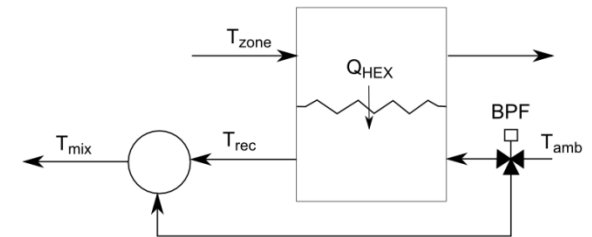
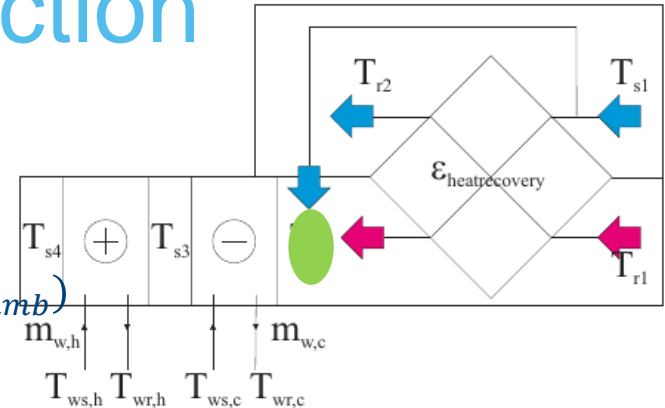
$$\text{BPF}^N = \frac{T_{vent,set}^N - \epsilon (T_{zone}^N - T_{amb}) - T_{amb}}{\epsilon (T_{amb} - T_{zone}^N)} \quad \text{s.t.} \quad 0 \leq \text{BPF}^N \leq 1$$

- Additional power by heating or cooling coil

$$Q = \dot{m}_{vent}^N c_{p,a} (T_{vent,set}^N - T_{mix}^N)$$

- Cost function

$$P_{Fuel} = \eta Q \quad \text{or} \quad P_{el} = \frac{Q}{EER}$$



Non-linearities of cost function

Ventilation

- Neglect air dynamics
- Use min and max function to guess BPF stand:

$$P_{\text{fuel,boi}}^N = \max\left(\frac{1}{\eta} \dot{m}_{\text{vent}}^N c_{p,a} (T_{\text{vent,set}}^N - \max((1 - \epsilon)T_{\text{amb}} + \epsilon T_{\text{zone}}^N, T_{\text{amb}})), 0\right)$$

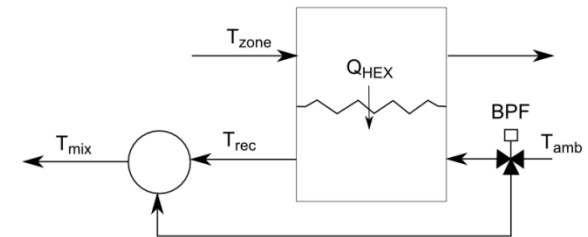
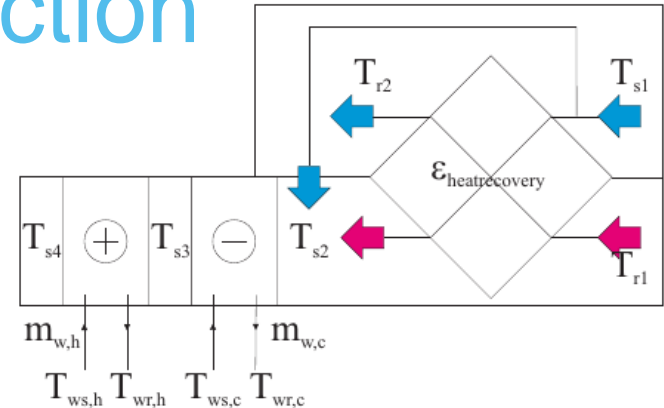
$$\text{s.t. } \frac{Q_{\text{heaUnit,nom}}}{\eta} \geq P_{\text{fuel,boi}}^N$$

$$P_{\text{el,chi LT}}^N = \max\left(\frac{1}{EER} \dot{m}_{\text{vent}}^N c_{p,a} (\min((1 - \epsilon)T_{\text{amb}} + \epsilon T_{\text{zone}}^N, T_{\text{amb}}) - T_{\text{vent,set}}^N), 0\right)$$

$$\text{s.t. } \frac{Q_{\text{cooUnit,nom}}}{EER} \geq P_{\text{el,chi LT}}^N$$

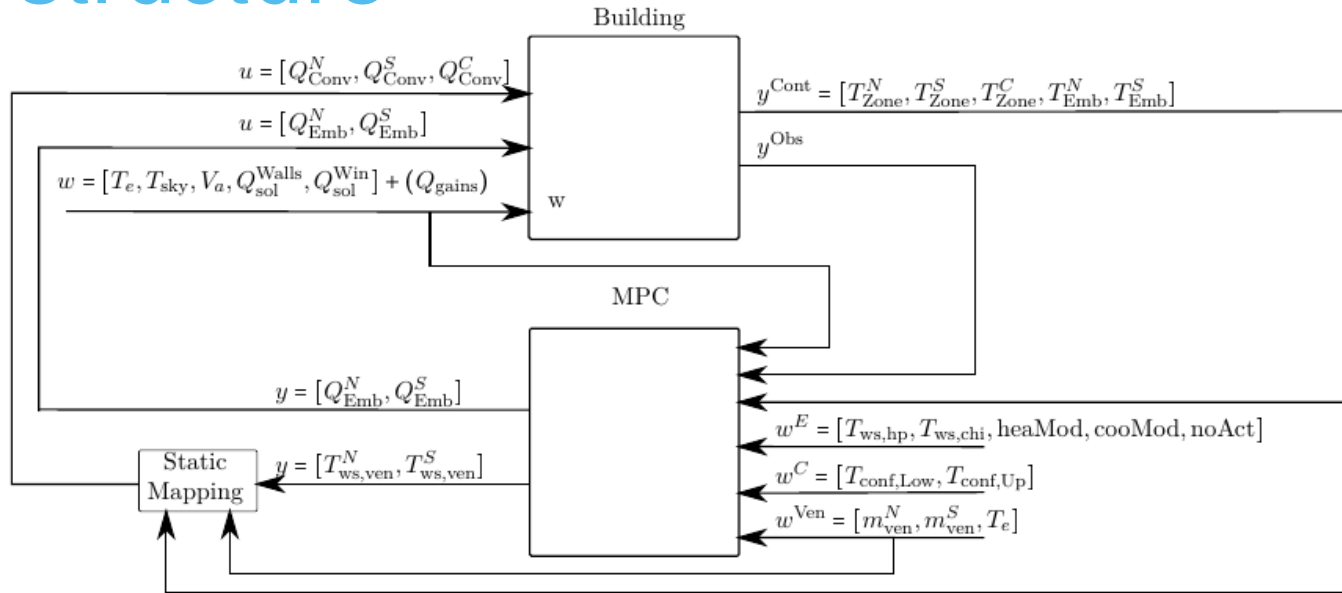
→ Non convex, but:

- if heating, mostly $T_{\text{amb}} < T_{\text{rec}} \rightarrow$ Use heat recovery
- if cooling, mostly $T_{\text{amb}} < T_{\text{rec}} \rightarrow$ Don't use heat recovery
- Cost function: $P_{\text{fuel,boi}} = \max\left(\frac{1}{\eta} \dot{m}_{\text{vent}} c_{p,a} (T_{\text{vent,set}} - (1 - \epsilon)T_{\text{amb}} - \epsilon T_{\text{zone}}), 0\right)$
 $P_{\text{el,chi LT}} = \max\left(\frac{1}{EER} \dot{m}_{\text{vent}} c_{p,a} (T_{\text{amb}} - T_{\text{vent,set}}), 0\right)$
- Notice: if $0 < BPF < 1 \rightarrow P_{\text{fuel}} = P_{\text{el}} = 0$

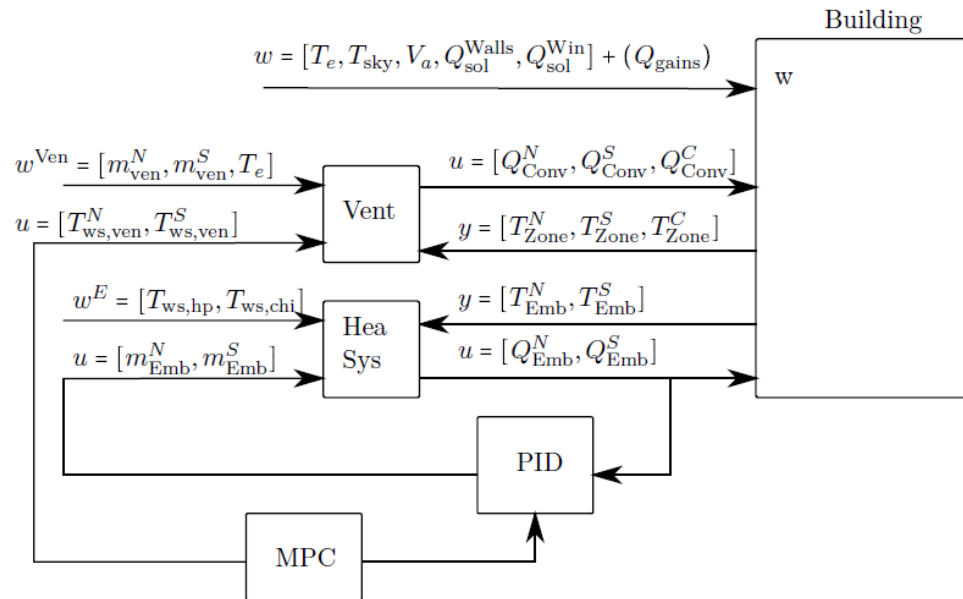


MPC structure

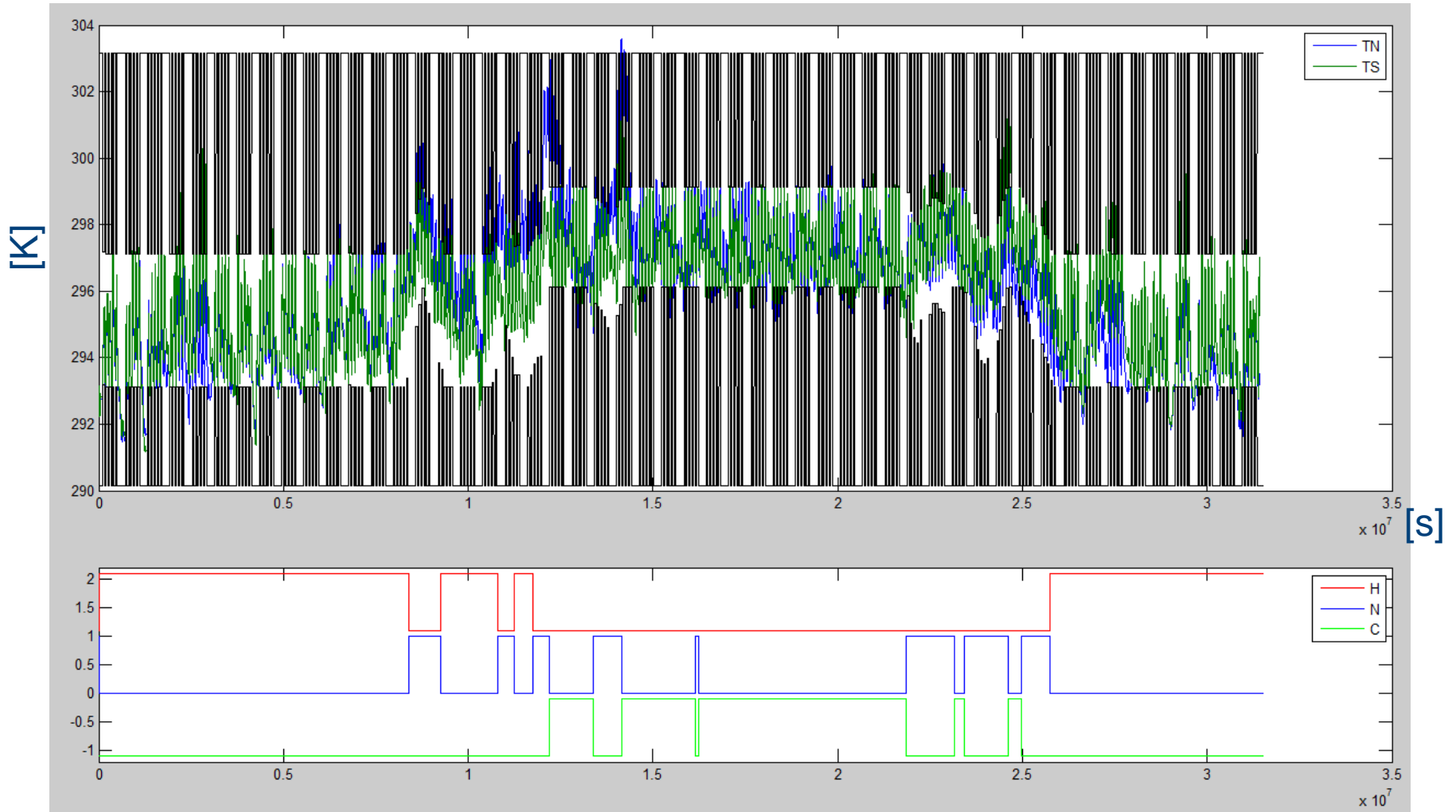
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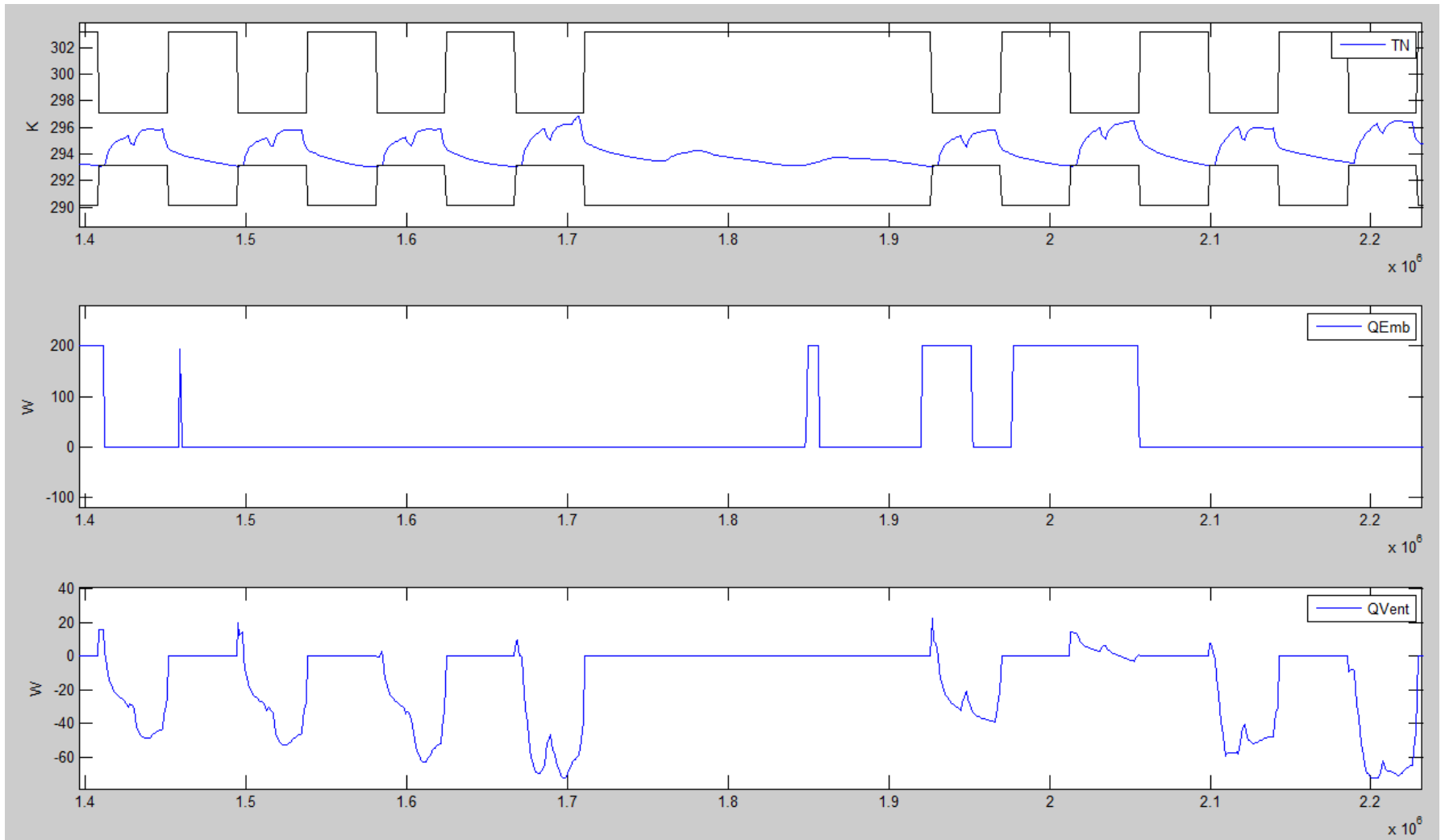
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MPC results



MPC results



Conclusion

- Strong non-linearities in HVAC
- Hybrid systems require more accurate cost function
- Good approximations based on physical insights for ventilation
- Hierarchical MPC

- Loss of optimality due to non-optimal \dot{m} , $T_{ws, hp}$, $T_{ws, chi}$, modes

Questions?



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