

CH X : OPTIMAL EXPERIMENTAL DESIGN

REVIEW : NONLINEAR PAR. ESTIM.

$$\hat{\theta} = \arg \min_{\theta} \| M(\theta; u) - y \|_2^2$$

SIM. OUTPUT
 $M: \mathbb{R}^d \times \mathbb{R}^N \rightarrow \mathbb{R}^N$

OUTP. MEASUREMENTS
 $y \in \mathbb{R}^N$

(ASSUMING GAUSSIAN OUTPUT ERRORS)

$$\Sigma = \text{cov}(\hat{\theta}) \approx G_y^2 \cdot (J(\hat{\theta}; u)^T \cdot J(\hat{\theta}; u))^{-1}$$

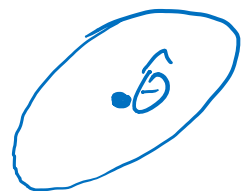
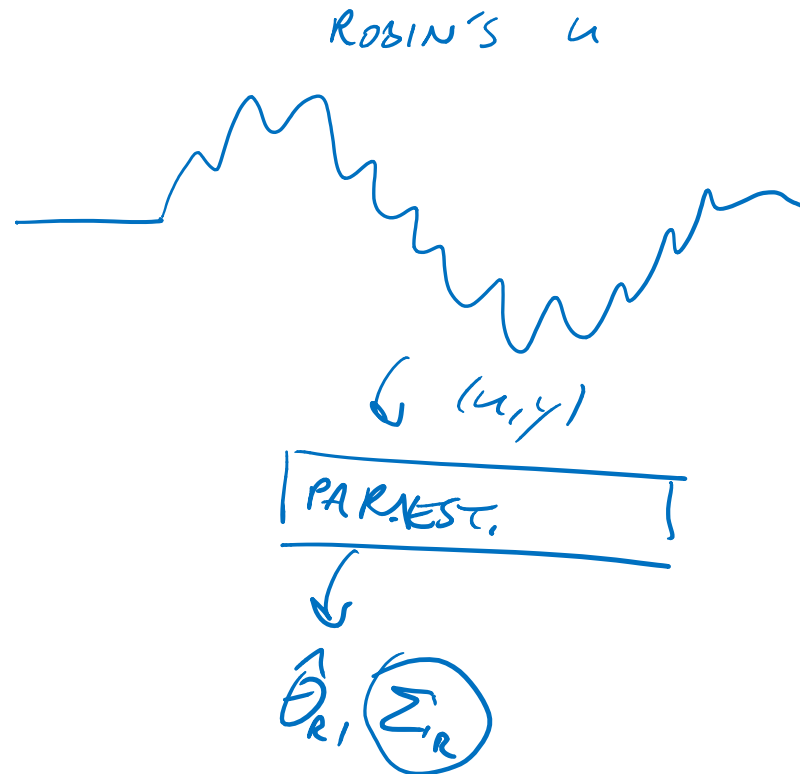
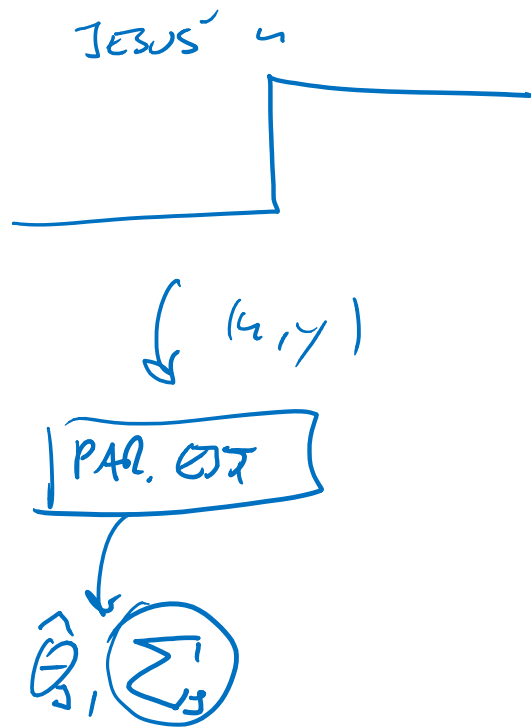
$$J(\theta; u) = \frac{\partial M}{\partial \theta}(\theta; u)$$

SO FAR, MEASUREMENTS WERE GIVEN (u, y FIXED)

OFTEN, WE CAN DECIDE ON u AND DESIGN OUR EXPERIMENTS.

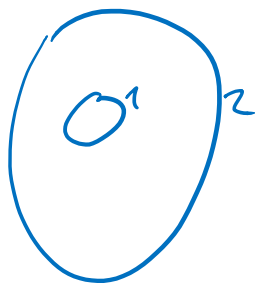
QUESTION: WHAT IS A "GOOD" EXPERIMENT?
 "OBJECTIVE FUN" FOR EXP. DESIGN

EX:

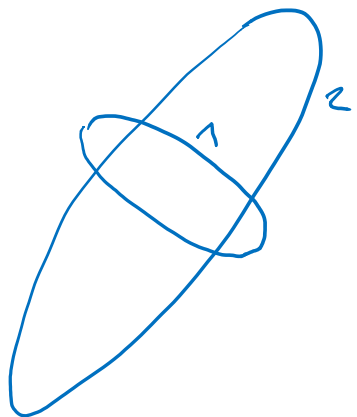


EXP. IS "BETTER" IF COV. MATRIX Σ IS "SMALLER"

Σ_1 IS "SMALLER" THAN Σ_2 IF $\begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix}$ $\Leftrightarrow \Sigma_1 \prec \Sigma_2 \Leftrightarrow 0 \prec \Sigma_2 - \Sigma_1$



1 IS BETTER



$\Sigma_i \in \mathbb{R}^{d \times d}$ IS POS. DEF. MATRIX,

1) CAN COMPARE TWO SUCH MATRICES WITH MATRIX INEQUALITIES ($\Sigma_1 \preceq \Sigma_2$)

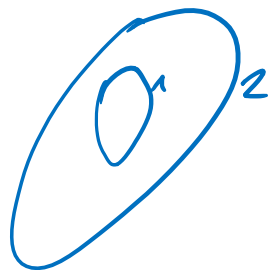
2) FOR MANY MATRIX PAIRS, NEITHER $\Sigma_1 \preceq \Sigma_2$ NOR $\Sigma_2 \preceq \Sigma_1$ HOLDS (UNDECIDED WHICH IS BETTER)

B) SPACE OF POS. DEF. MATRICES IS "HALF-ORDERED"

NEED "SCALAR" CRITERION $\phi(\Sigma)$ TO COMPARE, E.G. ELLIPSOID VOLUME $\in \mathbb{R}$

DEF. FOR GIVEN CRIT. $\phi: \mathbb{R}^{d \times d} \rightarrow \mathbb{R}$, WE SAY " Σ_1 BETTER Σ_2 " IFF " $\phi(\Sigma_1) < \phi(\Sigma_2)$ "

REASONABLE CRITERIA ϕ SATISFY:



$$\Sigma_1 \prec \Sigma_2 \Rightarrow \phi(\Sigma_1) < \phi(\Sigma_2)$$



SOME POSSIBILITIES FOR ϕ :

A-CRITERION: $\phi_A(\Sigma) = \underline{\text{trace}(\Sigma)} = \sum_{i=1}^d \Sigma_{ii} = \text{SUM OF EIGENVALUES}$

$$\Sigma = \begin{pmatrix} \cdot & & \\ & \cdot & \\ & & \ddots \\ & & & \cdot \end{pmatrix}$$

D-CRITERION: $\phi_D(\Sigma) = \text{PRODUCT OF EIGENVALUES} = \text{VOLUME} = \underline{\underline{\det(\Sigma)}}$

⋮

IN PRACTICE, NEED TO SCALE PARAMETERS, E.G. BY A SCALING MATRIX $S = \begin{pmatrix} s_1 & \dots & s_1 \end{pmatrix}$ WITH $s_i > 0$ OF APPR. UNITS. $\Sigma \rightarrow \underline{\underline{S^{-1} \cdot \Sigma \cdot S^{-1}}}$ (FOR A-CRITERION, THIS IS NECESSARY).

IDEA OF OPT. EXP. DESIGN: MINIMIZE $\phi(\Sigma)$ BY CHOOSING u

$\phi(\Sigma)$ DEPENDS ON Σ . $\Sigma = G_y^2 \cdot (J^T J)^{-1}$

Σ DEP. ON G_y^2 AND J . ASSUME G_y^2 FIXED. E.G. $G_y^2 = 1$

J DEP. ON θ AND u . $J = \frac{\partial M}{\partial \theta}(\theta; u)$

ASSUME θ FIXED AT OUR BEST AVAILABLE GUESS, $\theta = \bar{\theta}$

$$\phi\left((J(\bar{\theta}; u)^T \cdot J(\bar{\theta}; u))^{-1}\right) =: f(u)$$

OPT. EXP.

$$u = \arg \min_u f(u)$$

J DOES NOT DEPEND ON y !

AIM OF COMP. DERO:

- COMP. JESUS' SIGNAL u WITH "OUR" u
- CHOOSE D-CRITERION (NO NEED FOR SCALING)

PLAN OF ATTACK:

WRITE $\Pi(\theta; u)$

$$\boxed{J(\theta; u)}$$

$$\text{COV}(\theta; u) \equiv \text{COV}(u)$$

(ASS. θ FIXED AT BEST EST.)

~~$$\phi(\text{COV}(\theta; u))$$~~

$$\phi(\text{COV}(u))$$