

## Multi-Rate Partial Differential Equations for the Solution of Oscillatory Optimal Control Problems

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The solution of optimal control problems involving highly oscillatory dynamics is numerically challenging since a large number of simulation steps are required to accurately simulate the fast oscillations over a long horizon. We want explore the possibility of formulating the dynamics as a multi-rate partial differential equation (MPDE). These can then be simulated using collocation methods where the solution is approximated by a combination of polynomials (for the slow timescale) and periodic basis functions (for the fast timescale). Such methods have been already used for the simulation of high-frequency circuits.

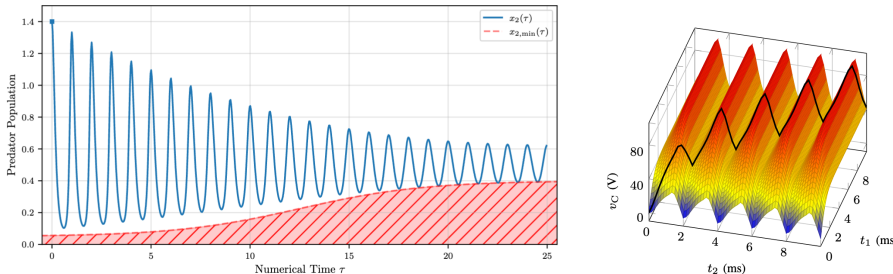


Figure 1: (left) A highly oscillatory solution of an optimal control problem, (right) Numerical solution of an MPDE in circuit simulation, from [1].

**Master topic:** We want to explore the formulation and solution of highly oscillatory optimal control problems using MDPEs, and how it compares against other (similar) approaches.

**Your skills:** Prior knowledge in systems, control, numerics and optimization is advisable. We will most likely be using a combination of Python along with the CasADi symbolic framework, so experience with these tools is recommended.

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